

# Modeling of Phenix EOL experiments with Serpent-DYN3D

E. Nikitin and E. Fridman

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**hzdr**

 **HELMHOLTZ**  
ZENTRUM DRESDEN  
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# Outline

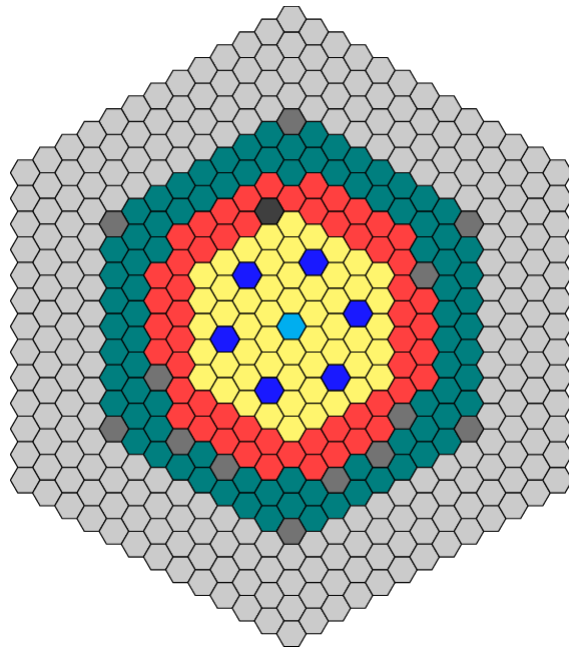
- Motivation
- Phenix End-of-Life core
- Serpent-DYN3D codes sequence
- Experiments and selected results
  - Control rod S-curves
  - Control rod shift tests
- Conclusions

# Motivation

- Reactor dynamics code DYN3D
  - 3D multi-group nodal diffusion
  - Internal thermal hydraulic model
  - Multi-physics coupling (e.g., ATHLET, CFX, TRANSURANUS, etc.)
  - Originally developed for LWRs
- Currently under extension for SFR applications
- Verification and validation is needed
  - Phenix EOL control rod withdrawal experiments

# Phenix EOL core

## Radial layout



Inner and outer core



Blanket



Primary and secondary control

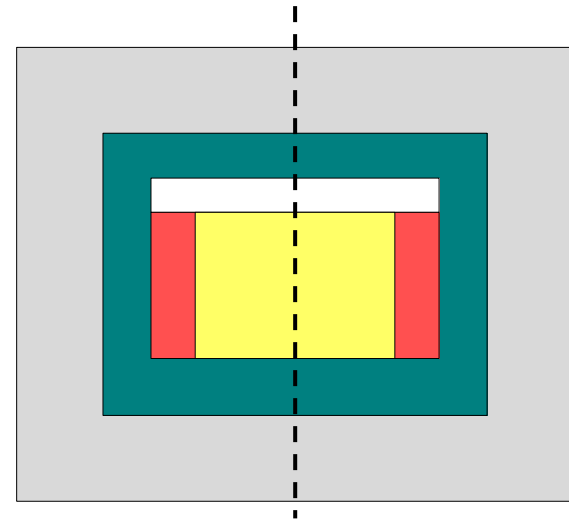


Reflectors



Sodium plenum

## Axial layout



Power, MWth	560
Inlet/Outlet temp, C	400/560
Fissile core diameter, m	1.50
Fissile core height, m	0.85
Fissile core volume, m <sup>3</sup>	1.51

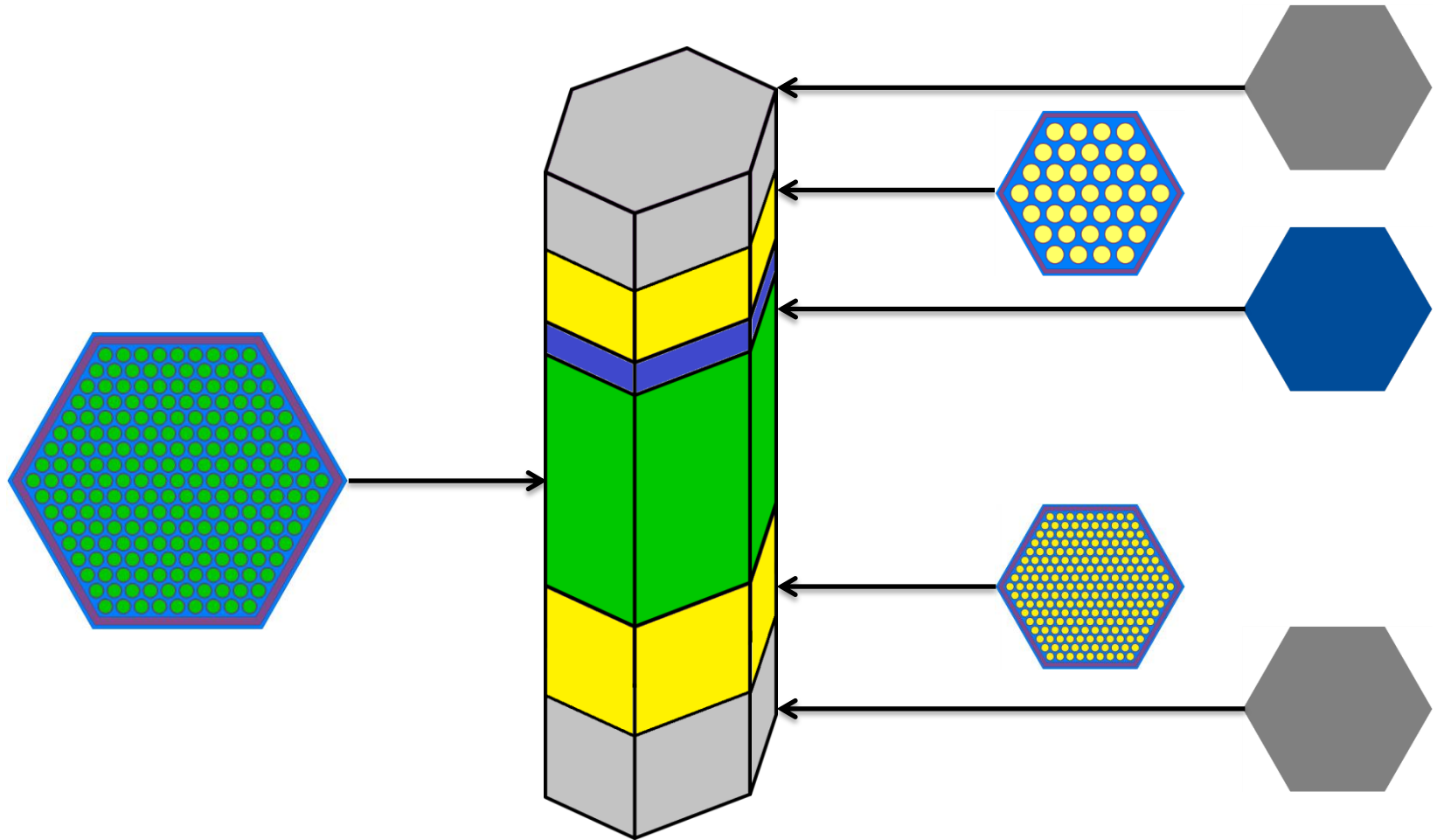
# Serpent-DYN3D codes sequence

# Calculation methodology

- Full core nodal diffusion solution with DYN3D
- Homogenized few-group cross sections (XS) for DYN3D
  - Using Serpent
  - 24 energy groups (subset of ECCO-33)
  - 2D and 3D lattice based models (next slides)
- Additional XS correction
  - To improve nodal diffusion solution
  - Superhomogenization (SPH) factors
    - CRs, first row of blankets, inside reflectors
- Reference
  - Full core Serpent solution
  - Measurements

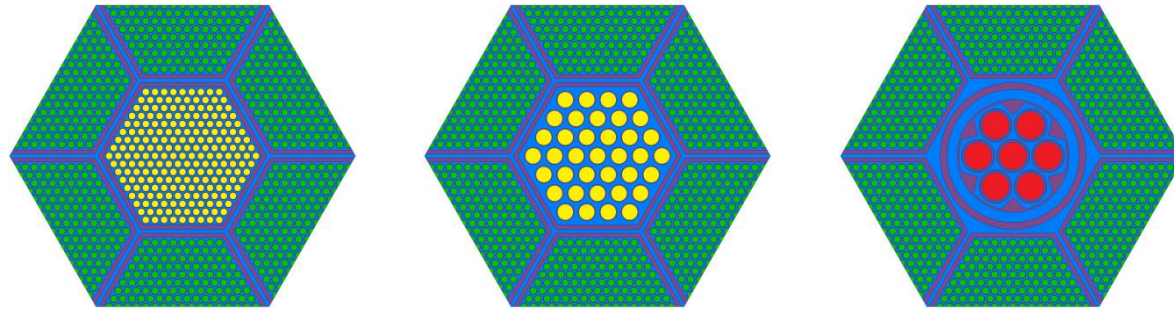
# Serpent models for XS generation

- Fuel material – 3D sub-assembly model

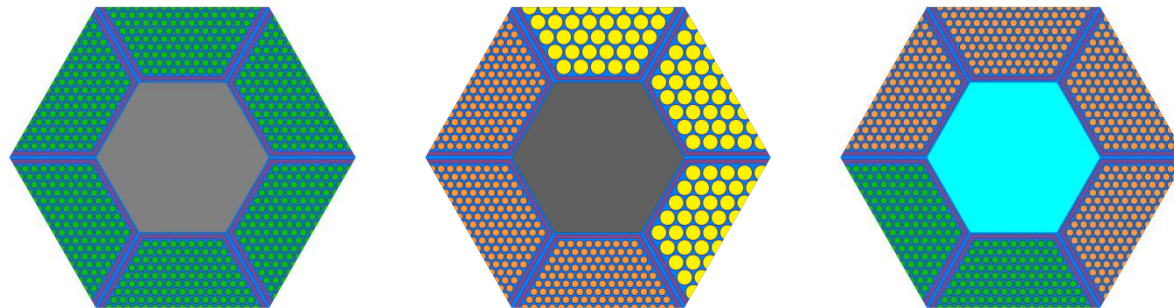


# Serpent models for XS generation

- Non-multiplying regions – 2D super-cell model
  - Blankets and Control rods



- Homogenized assemblies, Inside reflectors and Diluent

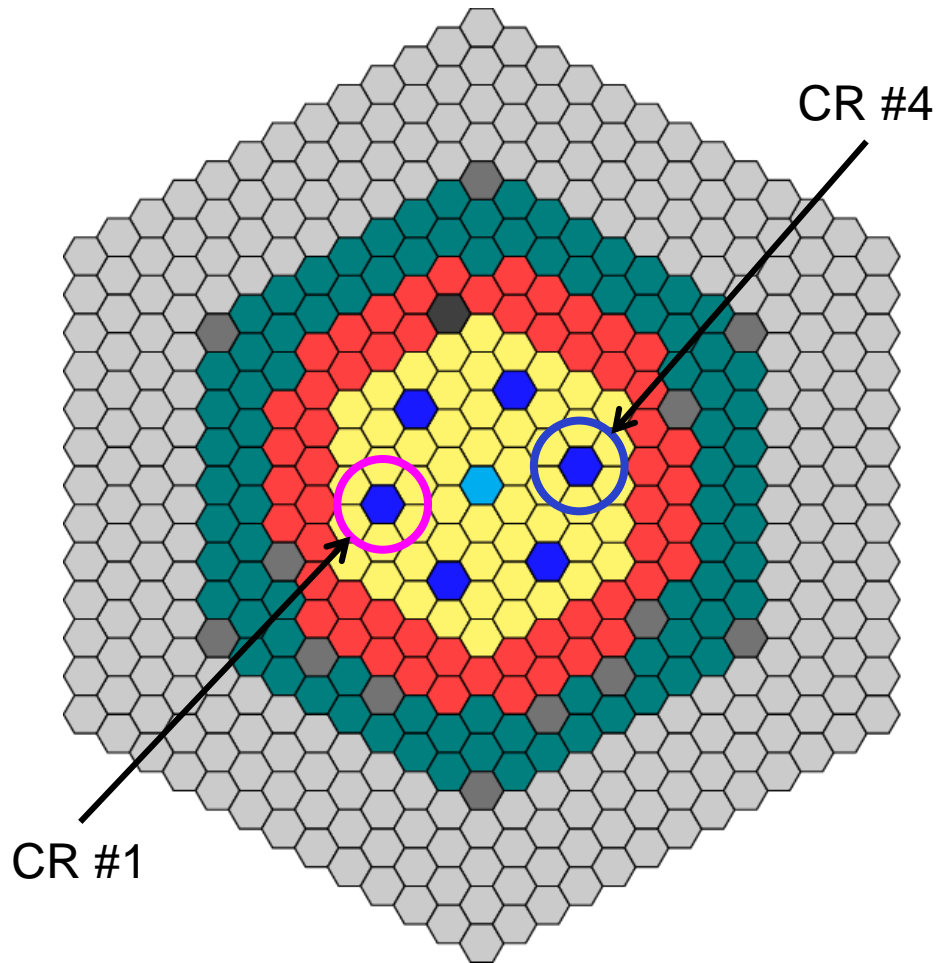




# Experiments and selected results:

## Control rod S-curves

# CR withdrawal – Off-power tests

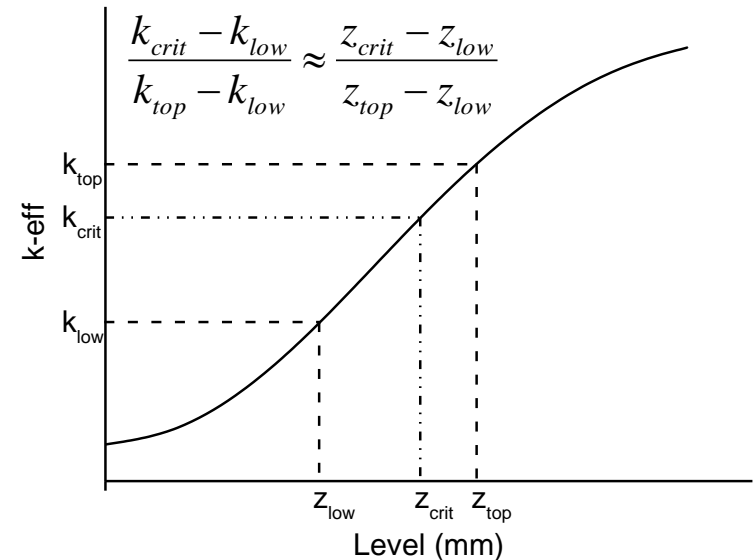


## Measurements

- Control rod worth
- Low power (~50 kW)
- Balancing method

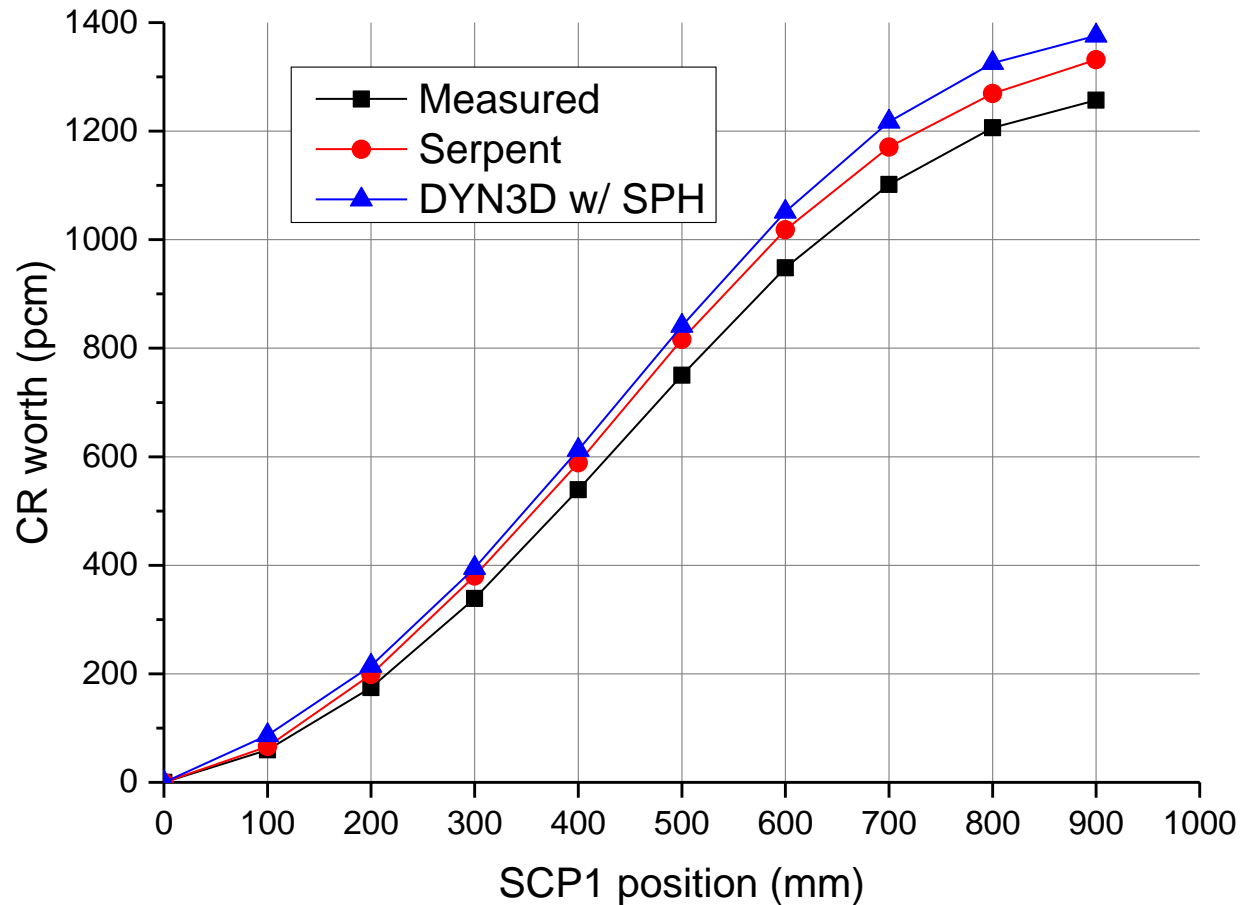
# Balancing method for Serpent and DYN3D

- Matlab script for automatization
- Criticality search with CR movement
- S-curve calculation
  - Start with two k-eff calculations: rodged and unrodged
  - Linear approximation for the next CR position
  - Several full core calculations
  - Starting with poor statistics for acceleration
  - Improve statistics when  $3\sigma$  confidence intervals overlap
- Calculation time (AMD 64x2300 MHz): ~1 day for 10-point S-curve



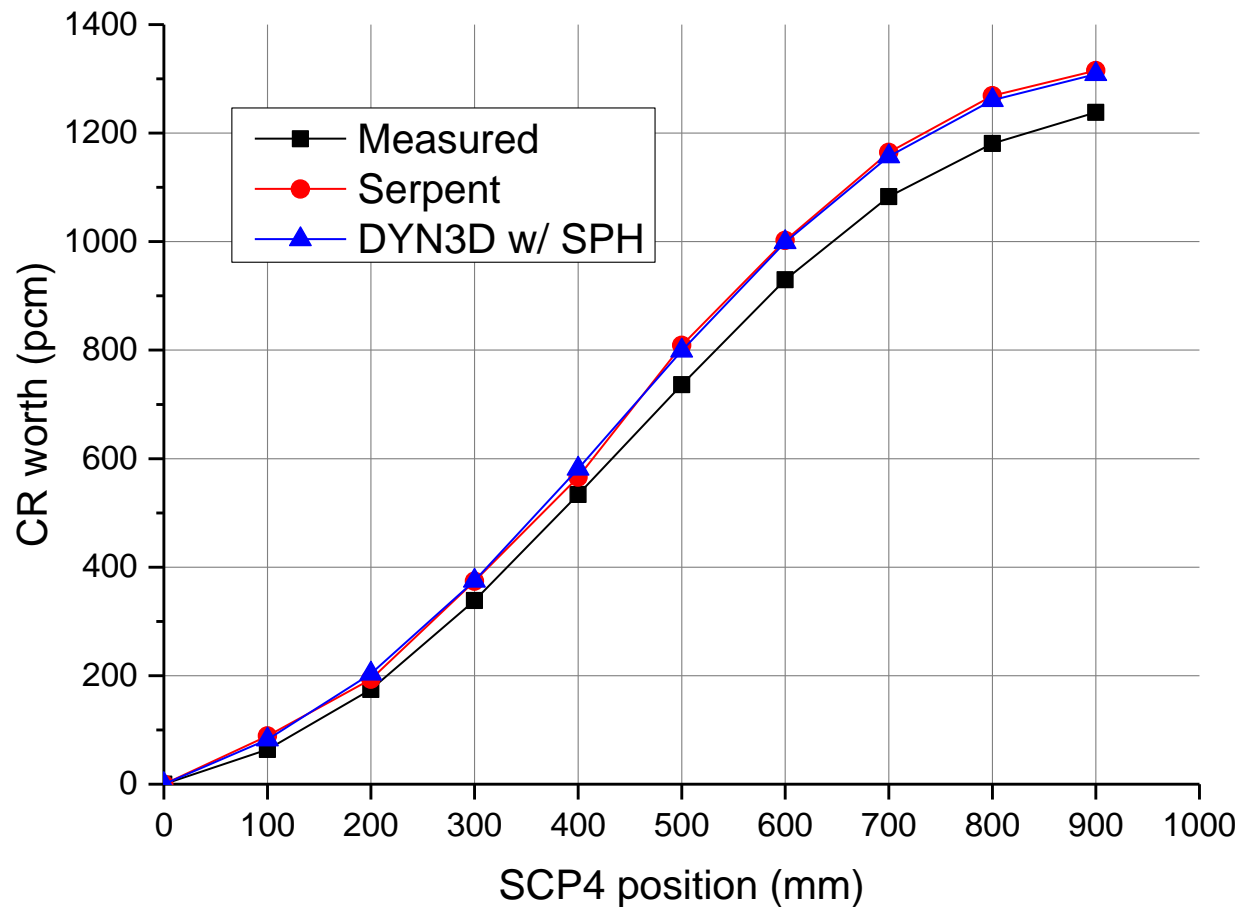
# Control rod #1 S-curve

Measured (pcm)	Serpent		DYN3D	
	CR worth	Diff. (pcm)	CR worth	Diff. (pcm)
1257	1331	74	1376	119



# Control rod #4 S-curve

Measured (pcm)	Serpent		DYN3D	
	CR worth	Diff. (pcm)	CR worth	Diff. (pcm)
1238	1315	77	1309	70



# **Experiments and selected results:**

## **Control rod shift tests**

# CR withdrawal – On-power tests

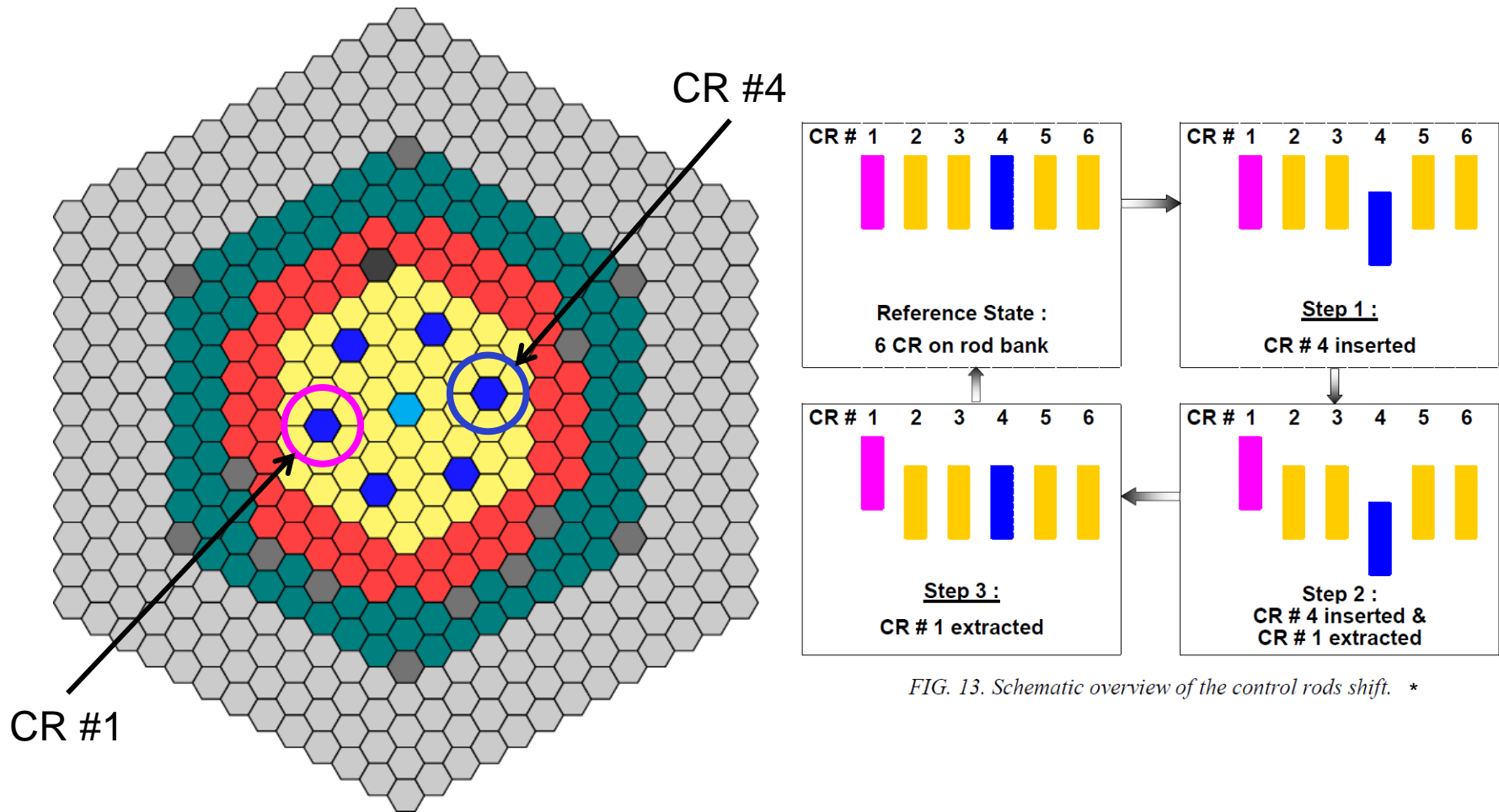
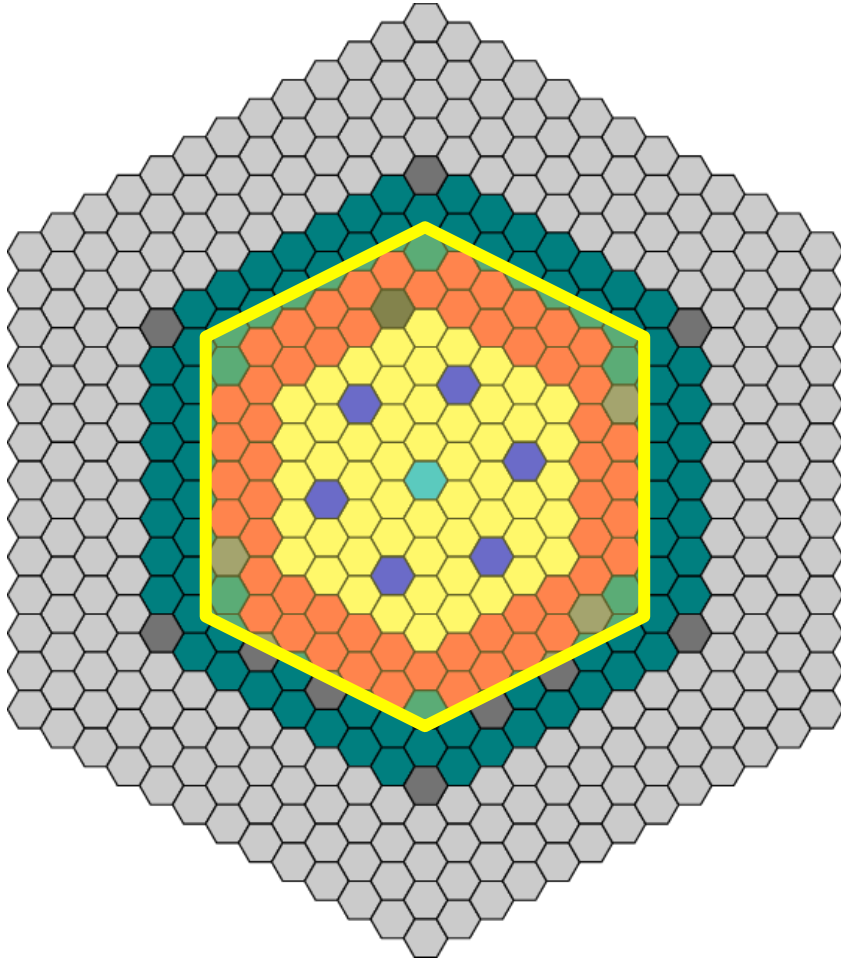


FIG. 13. Schematic overview of the control rods shift. \*

\* Fig. 13 was extracted from the final benchmark report

# CR withdrawal – On-power tests



## Measurements

- Sodium outlet temperature
- Thermocouples at outlet (120 S/As)
- Flow rate remained constant
- Power shape perturbations from:

$$P_i = \dot{m}_i \cdot C_p(Na) \cdot (T_{out} - T_{in})$$



# Core description deficiencies

- Average core description
  - Materials
  - Burnup
  - Temperatures
- $P_i = \dot{m}_i \cdot C_p(Na) \cdot (T_{out} - T_{in})$

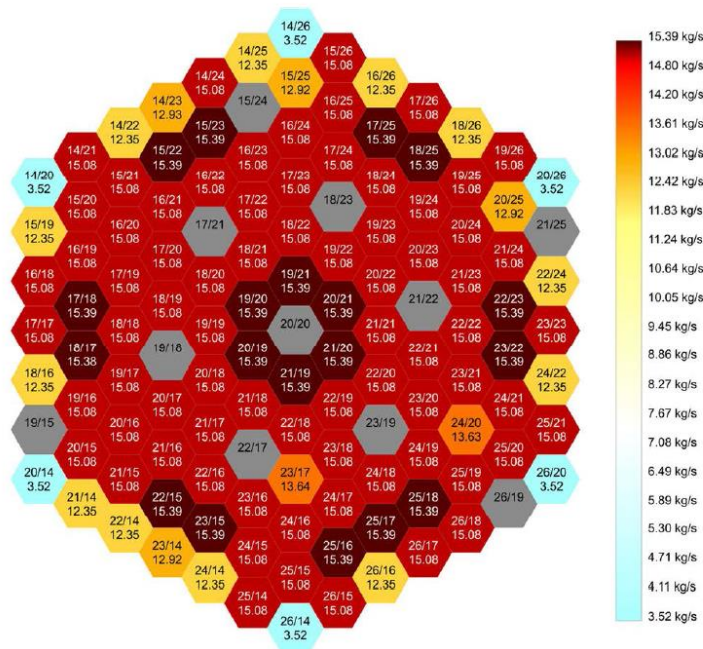


FIG. 30. Flows per S/A (initial state).

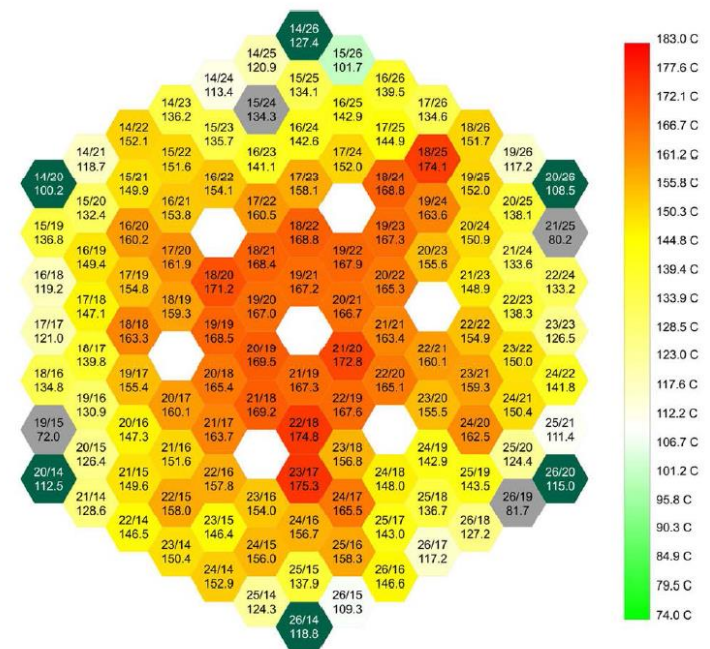
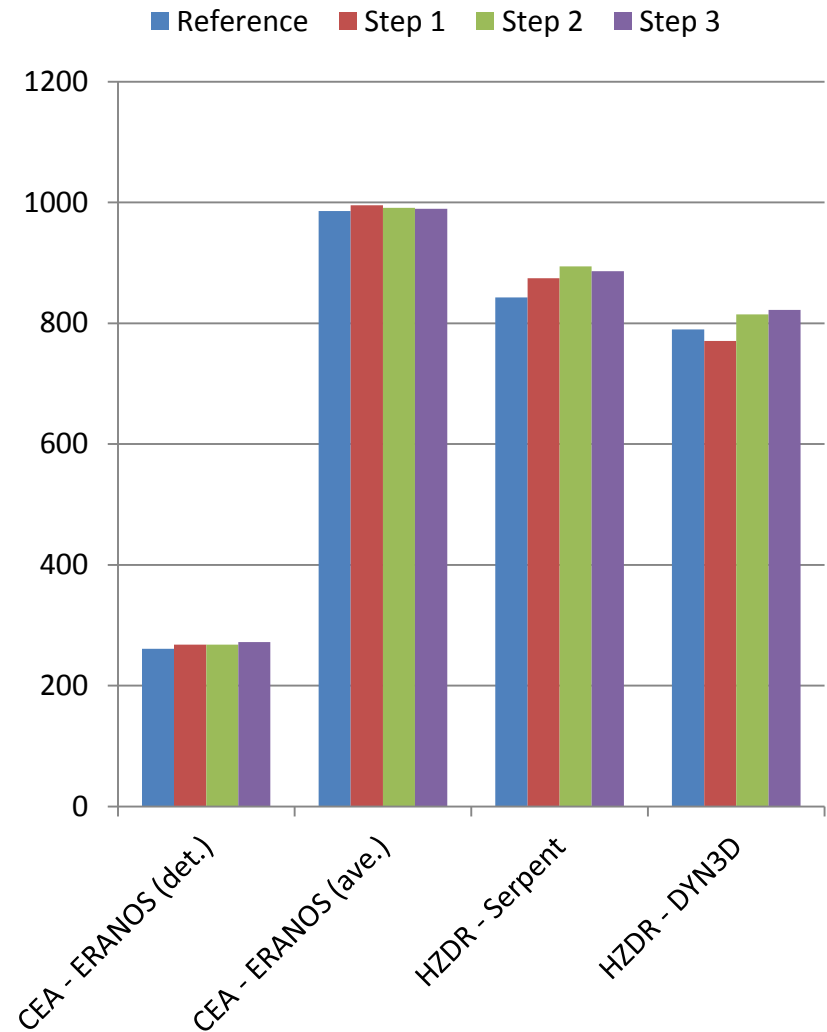


FIG. 12. Sodium heating per S/A - initial state.

\* Fig. 12 and 30 were extracted from the final benchmark report

# Core reactivity during all steps

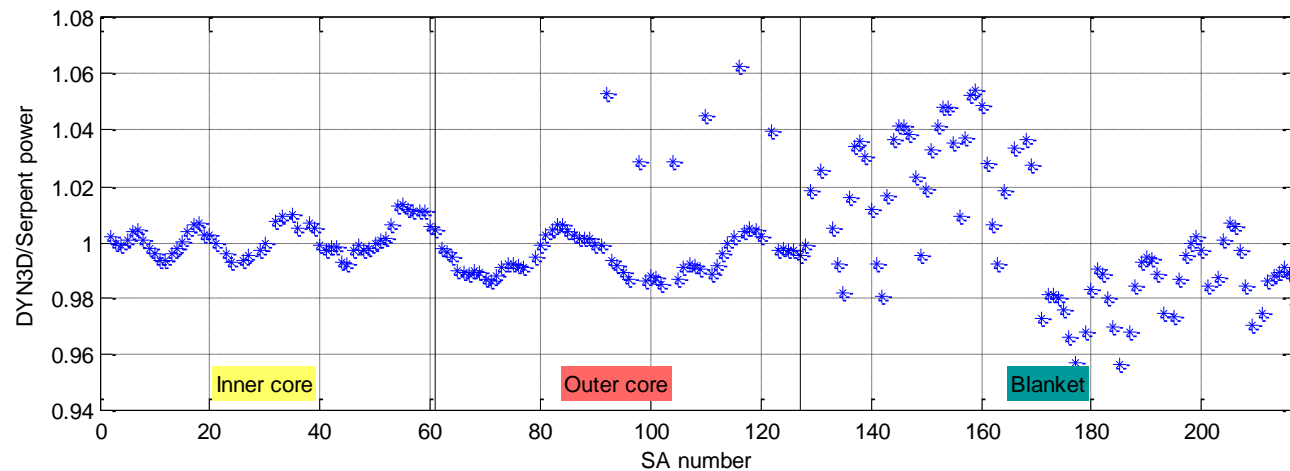
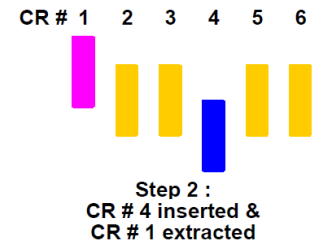
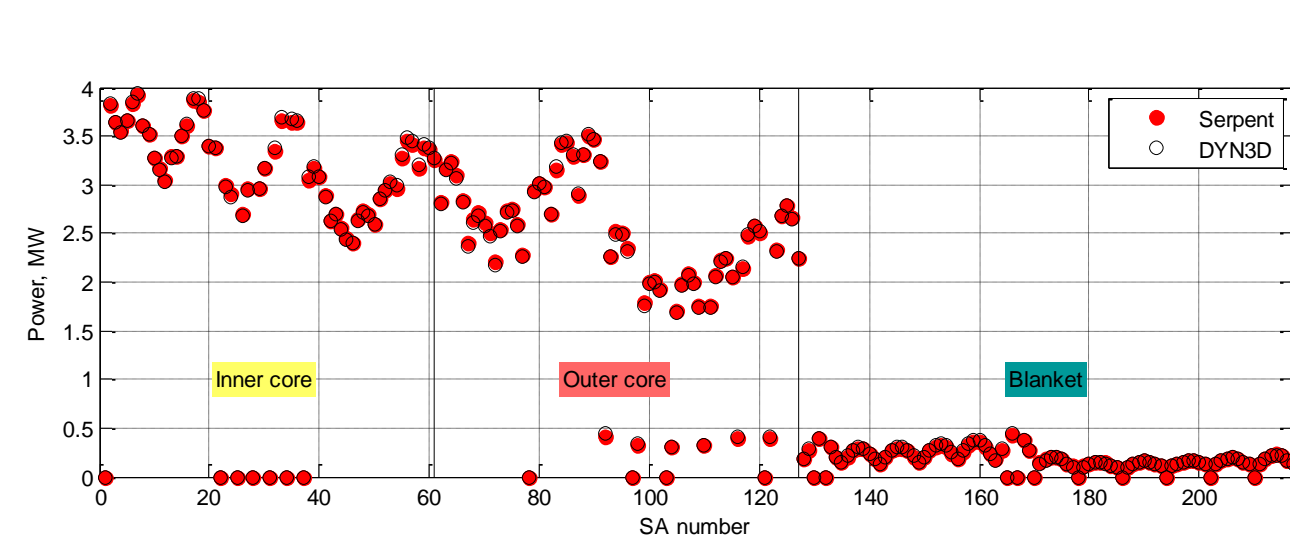
	Serpent, pcm	DYN3D, pcm	Difference, pcm
Reference state	843	790	-53
Step 1	874	771	-103
Step 2	894	815	-79
Step 3	886	822	-64



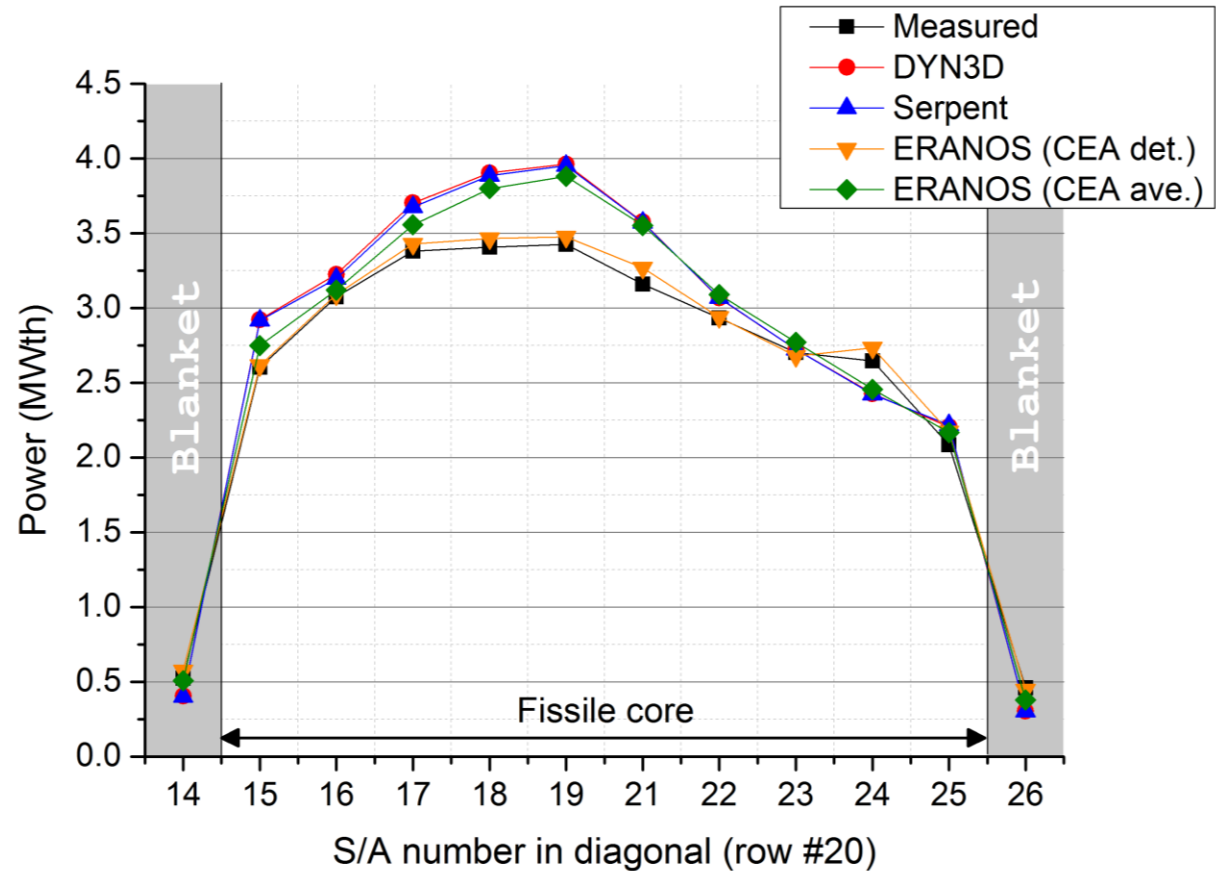
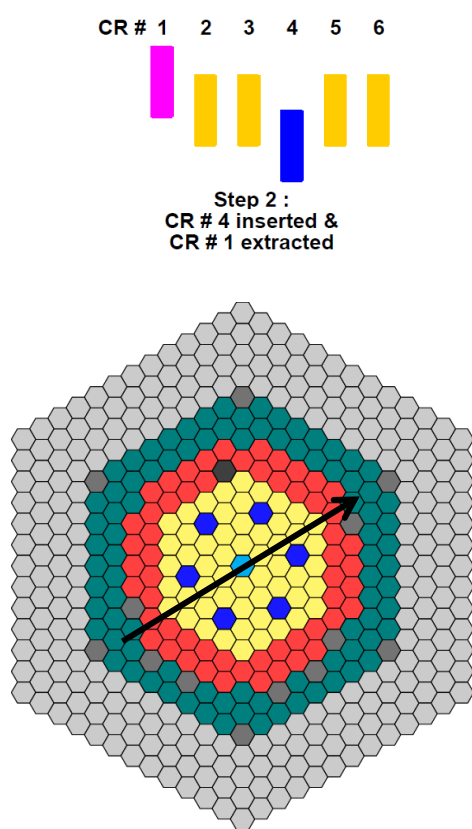
# Radial power distribution: DYN3D vs. Serpent

<b>Core</b>	Average relative difference, %	Maximal relative difference, %
	DYN3D vs. Serpent	DYN3D vs. Serpent
Reference state	0.33	1.15
Step 1	0.29	1.03
Step 2	0.34	1.15
Step 3	0.35	1.19
<b>Blanket</b>	Average relative difference, %	Maximal relative difference, %
	DYN3D vs. Serpent	DYN3D vs. Serpent
Reference state	1.56	4.45
Step 1	1.48	4.32
Step 2	1.57	4.73
Step 3	1.57	4.63

# Radial power distribution: DYN3D vs. Serpent

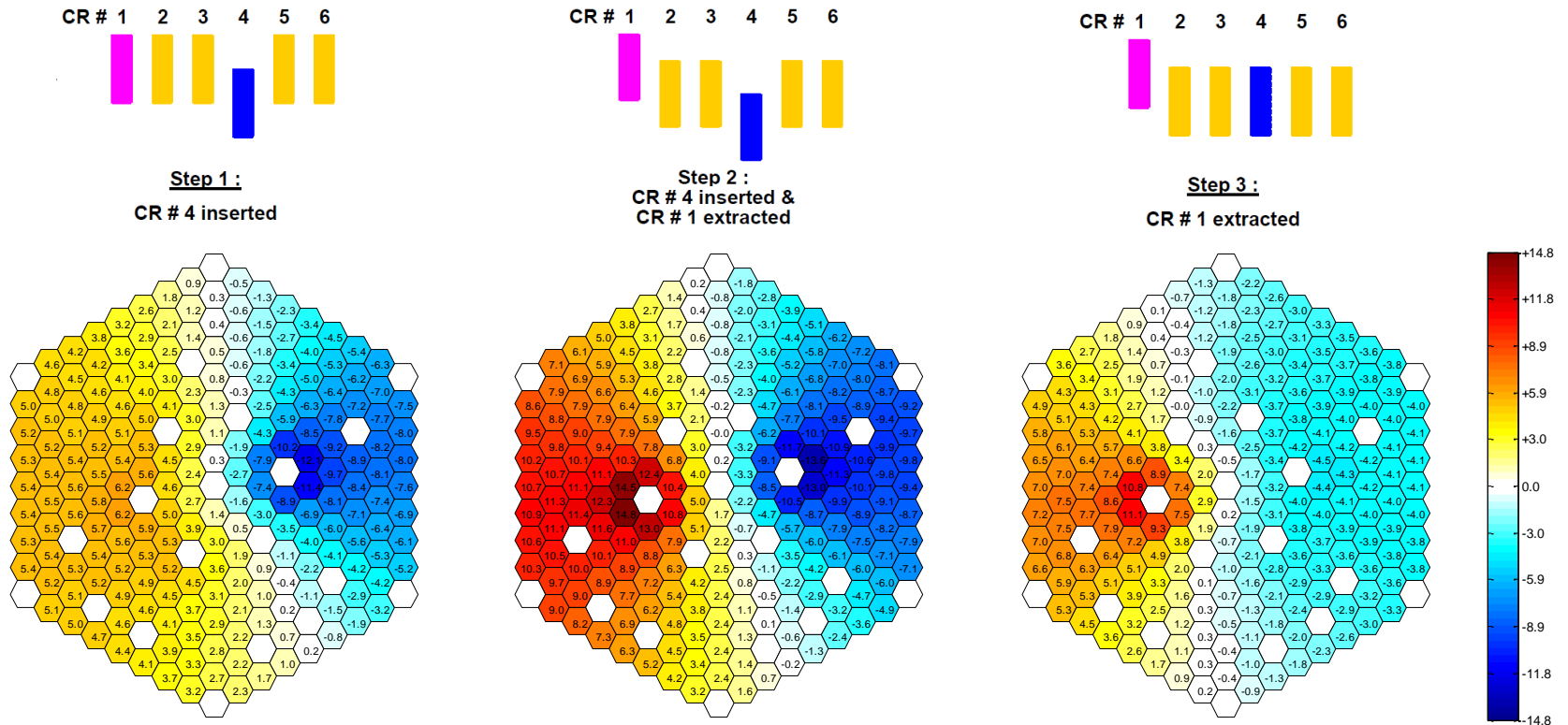


# Radial power distribution: Step 2



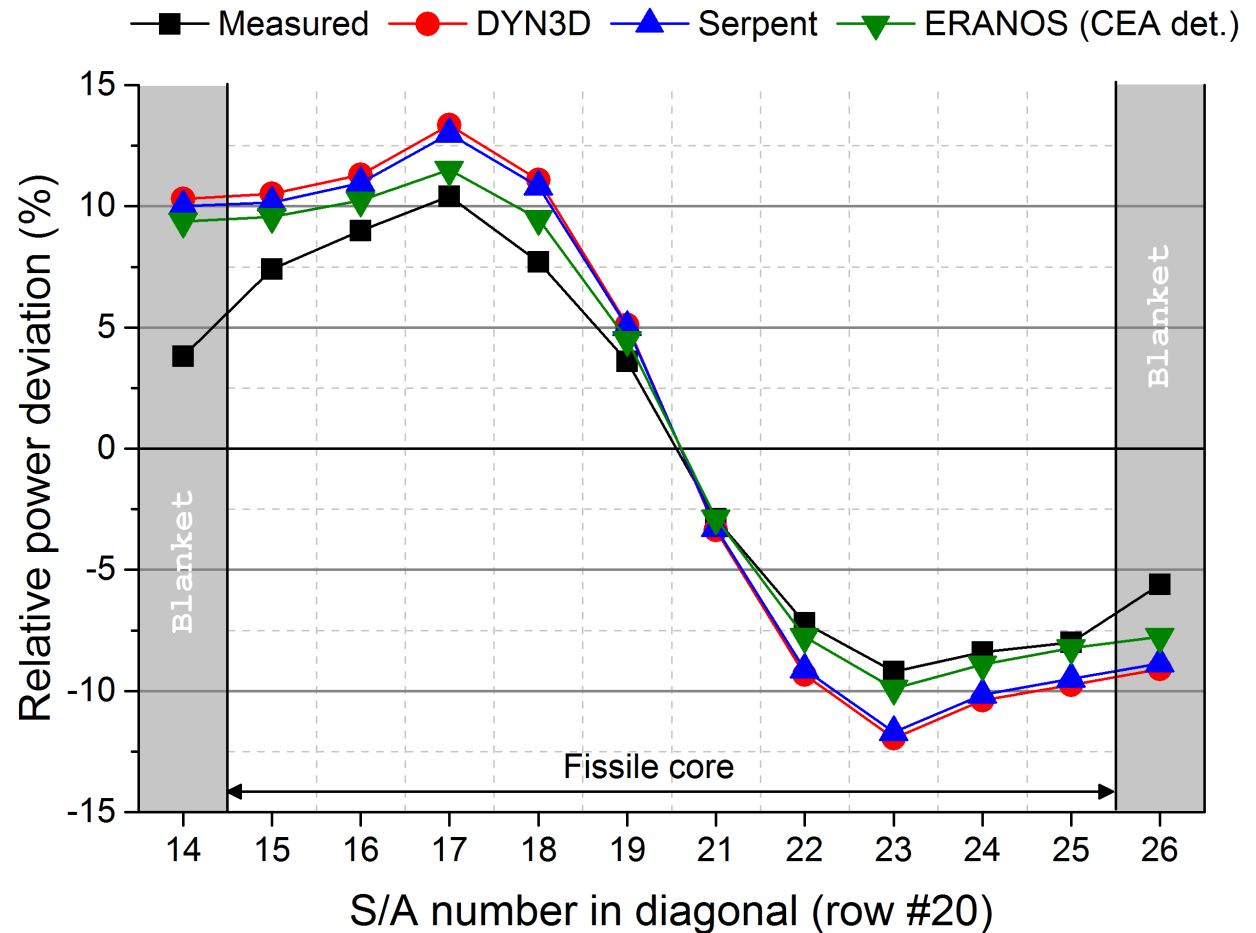
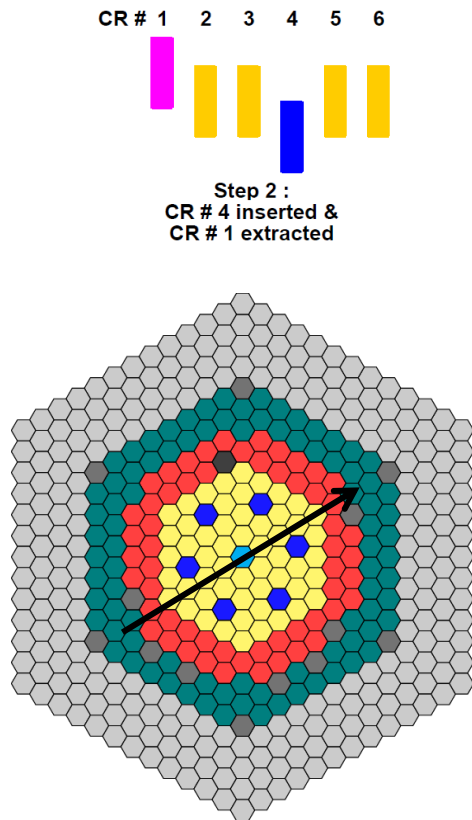
Note: The detailed core description was only available for CEA.

# Power deviation distribution



	Step 1 Serpent / DYN3D	Step 2 Serpent / DYN3D	Step 3 Serpent / DYN3D
Max. positive dev.	+6.23 / 6.22%	+14.78 / 15.23%	+11.07 / 11.35%
Max. negative dev.	-12.08 / 12.19%	-13.61 / 13.90%	-4.52 / 4.66%

# Radial power deviation profile: Step 2



# Conclusions

- The Phenix EOL CR withdrawal benchmark was calculated
- DYN3D nodal diffusion solution
  - XS generated with Serpent
  - SPH factors were used for first neighbor nodes facing fuel assemblies
  - Full core Serpent solution as reference
- Very good agreement between DYN3D and Serpent in general
- Good agreement for CR S-curves between DYN3D and experiment
- CR shift tests
  - Good agreement: Serpent-DYN3D vs. other benchmark participants (CEA)
  - High discrepancies compared to experiment due to averaged core model



# Thank you

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